



TECHMAN ROBOT

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A leading company in collaborative robot and vision technologies.

[Modbus Slave] J1 - J6 Torque value is added.

Outline

- Purpose

 - [Modbus Slave] J1 - J6 Torque value is added.

- Equipment

 - TM5 / TM12 /TM14

- Function operation

Function Operation

- J1~6 (Torque)

→ The torque value for each joint(unit:N-m)

| Torque | FC | Address ₁₀ | Address ₁₆ | Type | R/W | Note1 | Note2 |
|---------|----|-----------------------|-----------------------|-------|-----|-------|-------|
| Joint 1 | 04 | 7901~7902 | 1EDD~1EDE | Float | R | Dword | mNm |
| Joint 2 | 04 | 7903~7904 | 1EDF~1EE0 | Float | R | Dword | mNm |
| Joint 3 | 04 | 7905~7906 | 1EE1~1EE2 | Float | R | Dword | mNm |
| Joint 4 | 04 | 7907~7908 | 1EE3~1EE4 | Float | R | Dword | mNm |
| Joint 5 | 04 | 7909~7910 | 1EE5~1EE6 | Float | R | Dword | mNm |
| Joint 6 | 04 | 7911~7912 | 1EE7~1EE8 | Float | R | Dword | mNm |



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THANK YOU