



The Rule Change Of Hard Disk Save Data

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Introduction

➤ Purpose

When the hard disk is full, it can choose do not save the data or delete the oldest data then save the new data.

➤ Device Used

1.TM5

2.Techman SSD

➤ How to use

The screenshot displays the 'Hard Disk Setting' interface. The 'Stop status handling' section is highlighted with a red box, showing two radio button options: 'Do not save data' (unselected) and 'Delete from the oldest data' (selected). Below this is the 'Image Path Selection' section with a text input field containing 'TMROBOT:\' and a 'Select Path' button. Further down, there is a slider control for 'Stop when free space on hard disk is lower than:' set to '0 MB'. At the bottom, a 3D pie chart shows disk usage: 121535 MB of free space (green), 566 MB of filled space (blue), and a red 'Stop' indicator.

Category	Value	Unit
Free space	121535	MB
Filled space	566	MB

How to use

- Get into the HardDisk Setting.

The screenshot displays a control interface with several sections:

- Camera List:** Shows an 'Eye-in-Hand' camera with model 'TMCam_AFG1 (4103010937)'. It is calibrated.
- Task:** Contains icons for 'Camera Kit', 'Calibration', 'Task Designer', and 'HardDisk Setting'. The 'HardDisk Setting' icon is highlighted with a red box, and a red arrow points to it from the instruction above.
- Live Video:** A large black area representing the camera's live feed.
- Controller:** Shows a 3D model of a robot arm with joints labeled J1 through J6. Below the model is a control panel with the following data:

Joint	Base	Tool	IO	FreeBot
Jog Distance	Continuous		Speed 1.00%	
Joint Angle				
<input checked="" type="radio"/> J1	88.98	<input type="text"/>		
<input type="radio"/> J2	-29.37	<input type="text"/>		
<input type="radio"/> J3	115.85	<input type="text"/>		
<input type="radio"/> J4	4.97	<input type="text"/>		
<input type="radio"/> J5	91.87	<input type="text"/>		
<input type="radio"/> J6	5.11	<input type="text"/>		
<input type="button" value="-"/>		<input type="button" value="+"/>		<input type="button" value="Move"/>

How to use

- It can choose do not save data or delete the oldest data then save the new data.

The screenshot displays a control interface for a robot. A red box highlights the 'Hard Disk Setting' section, which includes a 'Stop status handling' option with two radio buttons: 'Do not save data' (selected) and 'Delete from the oldest data'. Below this is an 'Image Path Selection' field containing 'TMROBOT:\' and a 'Select Path' button. A slider indicates 'Stop when free space on hard disk is lower than: 0 MB'. A 3D pie chart shows disk usage: 'Free space : 121535 MB' (green), 'Filled space : 566 MB' (blue), and 'Stop' (red). A 'Manually Clear' button is at the bottom right of this section.

The 'Recorded Image List' section shows a list of recorded images:

- ▶ 0102
- ▶ apple
- ▶ apple_ming

The 'Controller' section features a 3D robot model with joints J1 through J6. Below the model is a table of joint angles and direct move controls:

Joint	Base	Tool	IO	FreeBot
Jog Distance	Continuous	Speed	1.00%	
Joint Angle		Direct Move		
<input checked="" type="radio"/> J1	88.98	<input type="text"/>	<input type="text"/>	<input type="text"/>
<input type="radio"/> J2	-29.37	<input type="text"/>	<input type="text"/>	<input type="text"/>
<input type="radio"/> J3	115.85	<input type="text"/>	<input type="text"/>	<input type="text"/>
<input type="radio"/> J4	4.97	<input type="text"/>	<input type="text"/>	<input type="text"/>
<input type="radio"/> J5	91.87	<input type="text"/>	<input type="text"/>	<input type="text"/>
<input type="radio"/> J6	5.11	<input type="text"/>	<input type="text"/>	<input type="text"/>

At the bottom of the Controller section are zoom controls (-, +) and a 'Move' button.

END