



Define DO status when robot stop

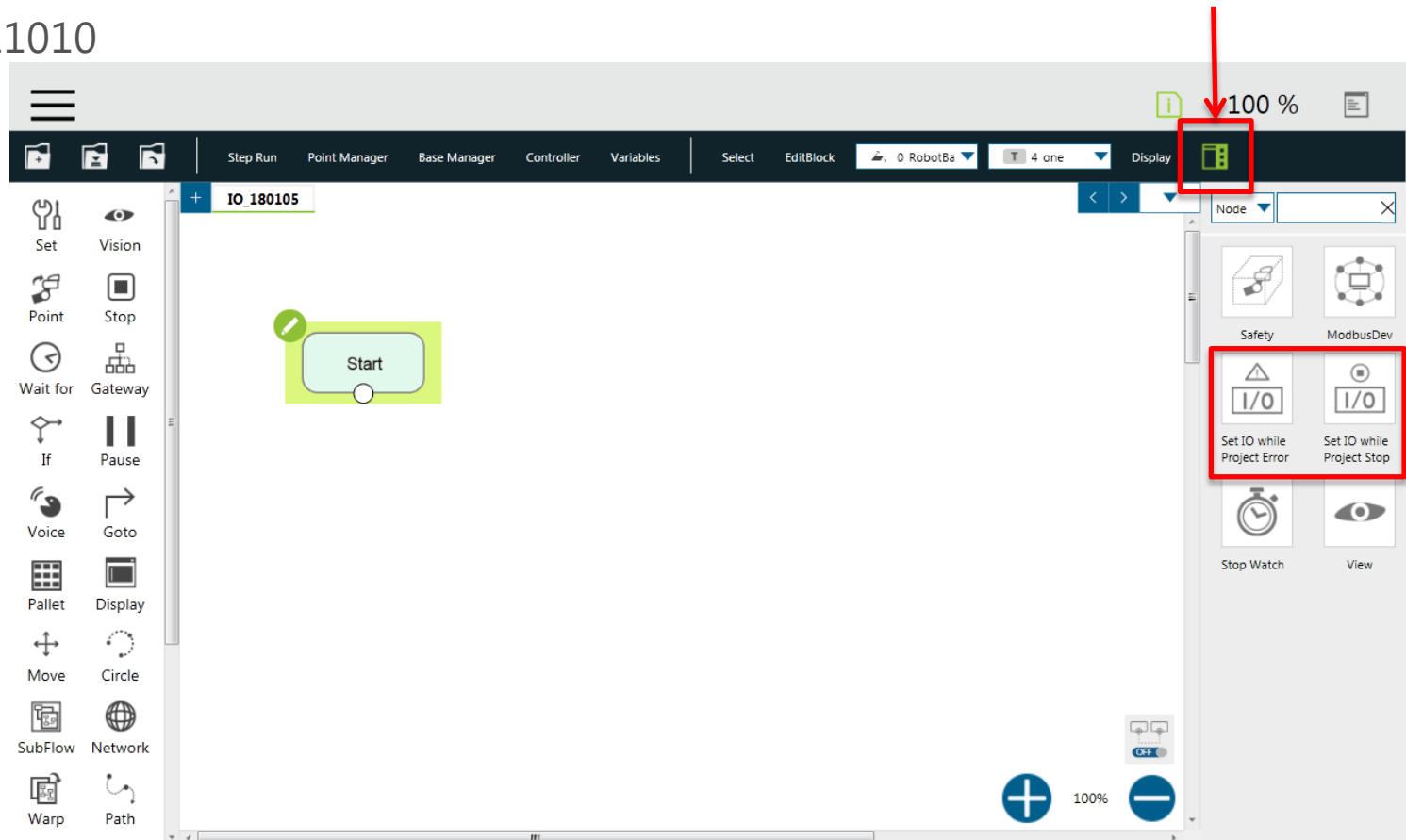
Introduction

➤ Purpose

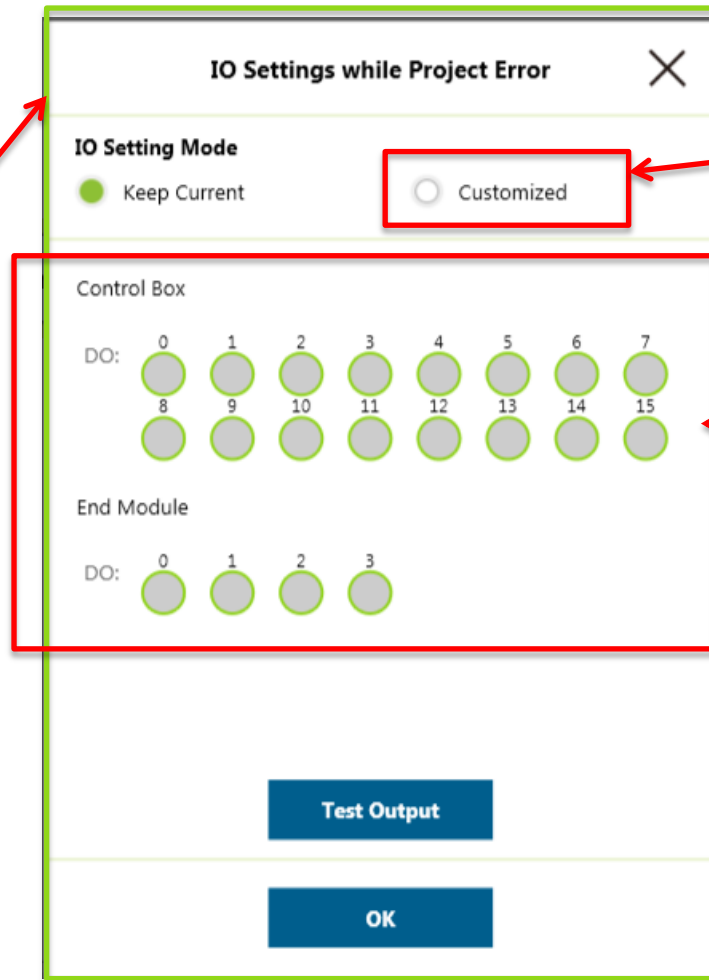
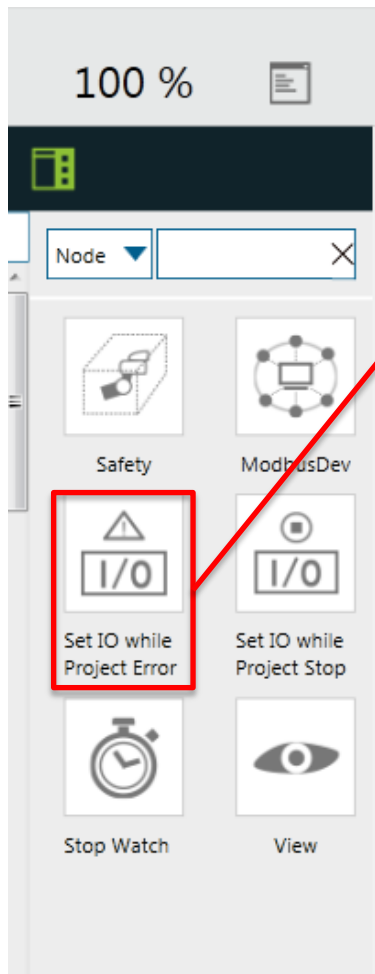
User can define DO status when robot stop.

➤ Equipment

TM5 HMI 1.64.1010



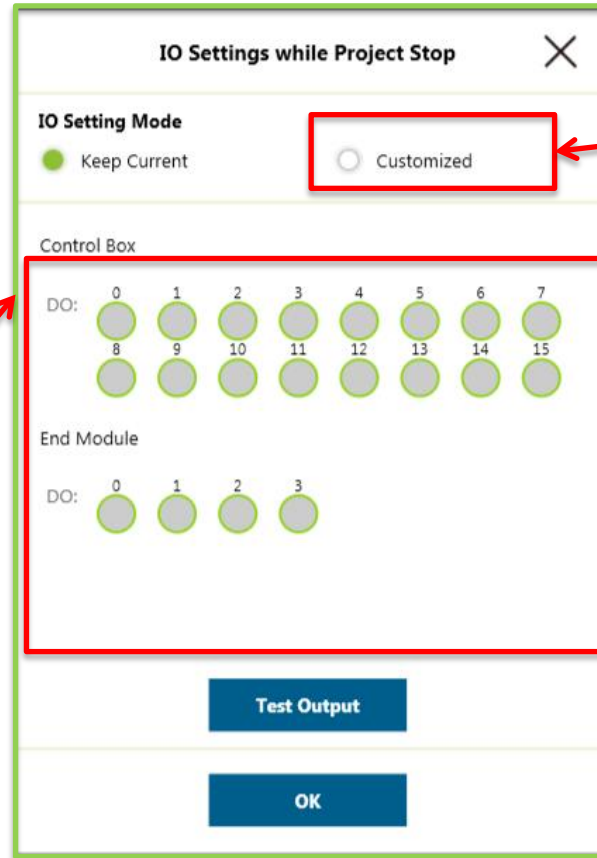
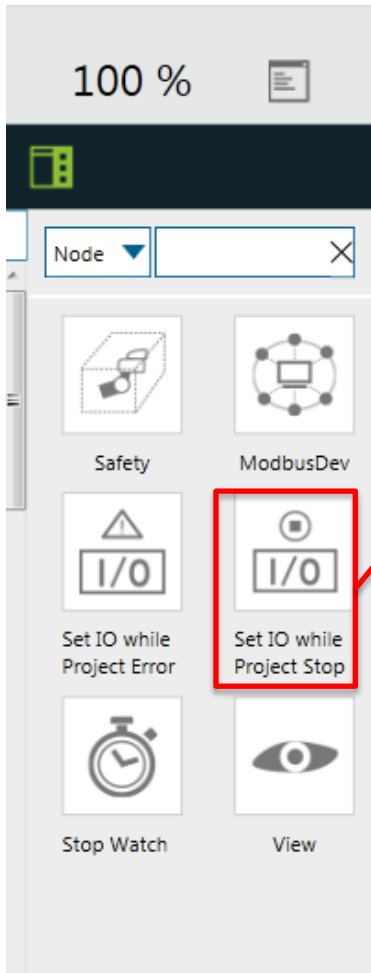
IO Setting while Project Error



Click 'Customized' for custom setting

Users can define DO status

IO Setting while Project Stop



Click 'Customized' for custom setting

Users can define DO status



- This setting is only applicable when there is a stop node in TM Flow or project is stopped manually.



Thank You